# Stability Analysis of an SIRI Epidemic Model with Distributed Latent Period

Amine Bernoussi<sup>1\*</sup>, Abdelilah Kaddar<sup>2</sup> and Said Asserda<sup>1</sup>

<sup>1</sup>Université Ibn Tofail, Faculté des Sciences, Département de Mathématiques, Kénitra, Morocco <sup>2</sup>Université Mohammed V de Rabat, Faculté des Sciences Juridiques, Economiques et Sociales - Salé, Morocco Email: amine.bernoussi@yahoo.fr

Abstract In this paper, we investigate the global asymptotic stability of the possible equilibria for an SIRI epidemic model with a distributed latent period and a general incidence function. By using the method of Lyapunov functions and the LaSalle invariance principle, we show that the global asymptotic stability is completely determined by the basic reproduction number  $R_0$ . The originality of this work is to have a basic reproduction number  $R_0$  which depends on the distribution of the latent period. Finally, we use a nonstandard discretization method of Mickens to illustrate numerically our theoretical results.

Keywords: Epidemic model, distributed time delay, Lyapunov function, global stability

# 1 Introduction

The epidemic models with time delay have long been an important subject for the mathematical researchers (see [1,2,3,4,5,6] for a discrete delay and [7,8] for a distributed delay), because many diseases, such as Influenza, Ébola and Tuberculosis, have a latent period, during which the individual is said to be exposed but not infectious. Therefore, it is important to ask the following question: how is it possible to model the latent period in order to improve the control of the spread of diseases?

In most statistical researches, motivated by this question, the latent period distribution may take different forms:

- The first one is a gamma distribution. For example, the latent period distribution of the avian influenza was modeled by a gamma distribution in agreement with the experiments [9].
- The second one is a log-normally distribution. For example, the latent period distribution of ebola was estimated to be log-normally distributed [10].

In this paper, we propose the following SIRI epidemic model with a distributed time delay and a relapse phenomenon, i.e. the return of signs and symptoms of a disease after a remission [11,12,13,14,6]:

$$\begin{cases} \frac{\mathrm{d}S}{\mathrm{d}t} = A - \mu S - f(S, I), \\ \frac{\mathrm{d}I}{\mathrm{d}t} = \int_0^h p(\tau) e^{-\mu\tau} f(S_\tau, I_\tau) \mathrm{d}\tau - (\mu + \gamma + \alpha)I + \delta R, \\ \frac{\mathrm{d}R}{\mathrm{d}t} = \gamma I - (\mu + \delta)R. \end{cases}$$
(1)

The initial condition for the above system is

$$S(\theta) = \varphi_1(\theta), \quad I(\theta) = \varphi_2(\theta), \quad R(\theta) = \varphi_3(\theta), \quad \theta \in [-h, 0]$$
 (2)

with  $\varphi = (\varphi_1, \varphi_2, \varphi_3) \in C^+ \times C^+ \times C^+$ , such that  $\varphi_i(\theta) \ge 0$   $(-\tau \le \theta \le 0, i = 1, 2, 3)$ .

Here C denotes the Banach space  $C([-h, 0], \mathbb{R})$  of continuous functions mapping the interval [-h, 0] into  $\mathbb{R}$ , equipped with the supremum norm. The non-negative cone of C is defined as  $C^+ = C([-h, 0], \mathbb{R}^+)$ , where  $\mathbb{R}^+ = \{x \in \mathbb{R} \mid x \geq 0\}$ .

Here  $\psi_{\tau} = \psi(t - \tau)$  for any given function  $\psi$ ,  $A = \mu N$ , where N is the total number of population, S is the number of susceptible individuals, I is the number of infectious individuals,  $\mu$  denotes birth and death rates,  $\alpha$  denotes death rate due to the disease, f(S, I) is the incidence function, i.e. the number of susceptible individuals infected through their contacts with the infectious individuals,  $\gamma$  is the recovery rate of the infectious individuals,  $\delta$  represents the rate that recovered individuals relapse and regain the infectious class,  $p(\tau)$  is the latent period distribution, which denotes the fraction of individuals who become infective  $\tau$  units of time after infection and h is a maximum time taken by infected individual to become able to transmit the infection (maximum latent period).

In model (1) the incidence function f(S, I) is a locally Lipschitz continuous function on  $\mathbb{R}^+ \times \mathbb{R}^+$  satisfaying f(0, I) = f(S, 0) = 0 for  $S \ge 0$ ,  $I \ge 0$  and the followings hold:

 $(H_1)$  f is a strictly monotone increasing function of  $S \ge 0$ , for any fixed I > 0, and f is a strictly monotone increasing function of  $I \ge 0$ , for any fixed  $S \ge 0$ ;

 $(H_2) \ \phi(S,I) = \frac{f(S,I)}{I}$  is a bounded and monotone decreasing function of I > 0, for any fixed  $S \ge 0$ , and  $K(S) = \lim_{I \to 0^+} \phi(S,I)$  is a continuous and monotone increasing function on  $S \ge 0$ .

This incidence function includes the following forms: The first one is the saturated incidence  $\frac{\beta SI}{d+S+I}$  [15], where  $\beta$  and d are the positive constants. The second one is the bilinear incidence  $\beta SI$  [16,17,18,19,20]. The third one is the saturated incidence  $\frac{\beta SI}{1+\alpha_1 S+\alpha_2 I}$  [15,21,22,23,17,24,25,26], where  $\alpha_1$  and  $\alpha_2$  are the positive constants. The effect of the saturation factor (refer to  $\alpha_1$  and  $\alpha_2$ ) stems from epidemic control and the protection measures. The fourth one is the standard incidence  $\frac{\beta SI}{N}$  [27,28].

Historically, Tudor [13] developed and analyzed qualitatively one of the first SIRI epidemic model for the spread of a herpes-type infection in either human or animal populations. This model consists of a system of non-linear ordinary differential equations with a bilinear incidence function and a constant total population. Based on the Tudor model, Moreira and Wang [29] extended a Tudor-model to include non-linear incidence functions and they derived sufficient conditions for the global asymptotic stability of the disease-free and endemic equilibria (see also [30,31,32,33,34] for particular incidence functions).

In [35,36], Van den Driessche et al. proposed an integro-differential equation to model a general relapse phenomenon in infectious diseases (see also [34,37]). The resulting model, in particular case, is a differential equation with discrete time delay, a constant population and a particular incidence functions (standard and bilinear). The basic reproduction number for this model is identified and some global results are obtained and the disease is shown to be uniformly persistent with the infective population size either approaching or oscillating about the endemic level. The effect of the discrete time delay in the epidemic models with a relapse rate has been taken into account in some recent studies ( see, for example [6,38,39]).

As observed in empirical data [9,10], the researchers modeled the latent period by introducing a distributed time delay in epidemic models and they demonstrated that distributed delay has the same effect as the discrete time delay (the basic reproduction number is independent on the distribution of the latent period). This implies that the distribution of latent period has no effect on the spread of infectious diseases [40,41,42].

In this paper we extend the global stability results presented in [6,38] to an SIRI epidemic model with a distributed time delay and a general incidence function. It is established that the basic reproduction number  $R_0$  depends on the distribution of the latent period, the incidence function and the relapse rate and it is shown that the global stability can be attained under suitable sufficient conditions on the incidence function and the threshold parameter  $R_0$ . The originality of this work is to introduce both a distributed time delay, a general incidence function and a relapse rate in the SIR epidemic model (see model (1)).

The rest of the paper is organized as follows. In Section 2, we establish the global stability of diseasefree and endemic equilibria. Section 3 gives a numerical analysis and concluding remarks concerning a comparison of a distributed SIRI model with a discrete SIRI model, and finally, in the section 4, we include our conclusions and our future researches.

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## 2 Global Stability Analysis of Delayed SIRI Model

System (1) always has a disease-free equilibrium  $P_0 = (\frac{A}{\mu}, 0, 0)$ . On the other hand, under the hypotheses  $(H_1)$  and  $(H_2)$ , if

$$R_0 := \frac{K(\frac{A}{\mu})\kappa(h)}{\eta} > 1, \tag{3}$$

then system (1) also admits a unique endemic equilibrium  $P^* = (S^*, I^*, R^*)$ , where  $S^*$ ,  $I^*$  and  $R^*$  satisfy the following system:

$$\begin{cases}
A - \mu S - f(S, I) = 0, \\
k(h)f(S, I) - (\mu + \gamma + \alpha)I + \delta R = 0, \\
\gamma I - (\mu + \delta)R = 0,
\end{cases}$$
(4)

with  $\kappa(h) = \int_0^h p(\tau) e^{-\mu\tau} d\tau$  and  $\eta = \mu + \gamma + \alpha - \frac{\gamma\delta}{\mu + \delta}$ .

**Remark 1.** The obtained basic reproduction number (3) depends on the distribution of the latent period  $(\kappa(h) = \int_0^h p(\tau)e^{-\mu\tau} d\tau)$ . In the literature, there is no formula similar to (3).

In this section, we will discuss the global stability of the disease-free equilibrium  $P_0$  and the endemic equilibrium  $P^*$  of system (1). Since  $\frac{d}{dt}(S+I+R) \leq A - \mu(S+I+R)$ , we have  $\limsup(S+I+R) \leq \frac{A}{\mu}$ . Hence we discuss system (1) in the closed set

$$\Omega :=: \{ (\varphi_1, \varphi_2, \varphi_3) \in C^+ \times C^+ \times C^+ : \|\varphi_1 + \varphi_2 + \varphi_3\| \le A/\mu \}.$$

It is easy to show that  $\Omega$  is positively invariant with respect to system (1). Next we consider the global asymptotic stability of the disease-free equilibrium  $P_0$  and the endemic equilibrium  $P^*$  of (1) by Lyapunov's functions, respectively.

**Proposition 2.** If  $R_0 \leq 1$ , then the disease-free equilibrium  $P_0$  is globally asymptotically stable.

Proof. Consider the following Lyapunov functional

$$V_0(t) = \int_0^h p(\tau)e^{-\mu\tau} \int_{\frac{A}{\mu}}^{S_\tau} \left(1 - \frac{K(\frac{A}{\mu})}{K(u)}\right) \mathrm{d}u \mathrm{d}\tau + I + \frac{\delta}{\mu + \delta}R$$
$$+ \int_0^h p(\tau)e^{-\mu\tau} \int_{t-\tau}^t \frac{K(\frac{A}{\mu})}{K(S(u))} f(S(u), I(u)) \mathrm{d}u \mathrm{d}\tau.$$

We will show that  $\frac{dV_0(t)}{dt} \leq 0$  for all  $t \geq 0$ . We have

$$\frac{\mathrm{d}V_0(t)}{\mathrm{d}t} = \mu \int_0^h p(\tau) e^{-\mu\tau} \left(1 - \frac{K(\frac{A}{\mu})}{K(S_{\tau})}\right) \left(\frac{A}{\mu} - S_{\tau}\right) \mathrm{d}\tau$$
$$+ \int_0^h p(\tau) e^{-\mu\tau} \frac{K(\frac{A}{\mu})}{K(S)} f(S, I) \mathrm{d}\tau - \eta I.$$

Furthermore, it follows from the hypothesis  $(H_2)$  that

$$\int_0^h p(\tau) e^{-\mu\tau} \frac{K(\frac{A}{\mu})}{K(S)} f(S, I) d\tau \le \int_0^h p(\tau) e^{-\mu\tau} \frac{K(\frac{A}{\mu})}{K(S)} \phi(S, I) I d\tau \le \eta I R_0.$$

By the hypothesis  $(H_2)$ , we obtain that

$$\left(1 - \frac{K(\frac{A}{\mu})}{K(S_{\tau})}\right)\left(\frac{A}{\mu} - S_{\tau}\right) \le 0,$$

where equality holds if and only if  $S = \frac{A}{\mu}$ . Therefore,  $R_0 \leq 1$  ensures that  $\frac{dV_0(t)}{dt} \leq 0$  for all  $t \geq 0$ , where  $\frac{dV_0(t)}{dt} = 0$  holds if  $(S, I, R) = (\frac{A}{\mu}, 0, 0)$ . Hence, it follows from system (1) that  $\{P_0\}$  is the largest invariant set in  $\{(S, I, R) | \frac{dV_0(t)}{dt} = 0\}$ . From the Lyapunov-LaSalle asymptotic stability, we obtain that  $P_0$  is globally asymptotically stable. This completes the proof.

**Proposition 3.** If  $R_0 > 1$ , then the endemic equilibrium  $P^*$  is globally asymptotically stable.

*Proof.* Firstly, we prove the existence and the uniqueness of the endemic equilibrium  $P^*$ . At a fixed point (S, I, R) of system (1), the following equations hold.

$$\begin{cases}
A - \mu S - f(S, I) = 0, \\
\kappa(h)f(S, I) - (\mu + \gamma + \alpha)I + \delta R = 0, \\
\gamma I - (\mu + \delta)R = 0.
\end{cases}$$
(5)

Substituting the third equation into the second equation of (5), we consider the following system:

$$\begin{cases}
A - \mu S - f(S, I) = 0, \\
\kappa(h)f(S, I) - (\mu + \gamma + \alpha - \frac{\gamma\delta}{\mu + \delta})I = 0, \\
R = \frac{\gamma I}{\mu + \delta}.
\end{cases}$$
(6)

Using the first and the second equations in (6), we conclude that

$$S = \frac{A}{\mu} - (\mu + \gamma + \alpha - \frac{\delta\gamma}{\mu + \delta}) \frac{I}{\mu\kappa(h)}.$$
(7)

Substituting the equation (7) into the second equation of (5), we have

$$g(I) := \frac{f(\frac{A}{\mu} - (\mu + \gamma + \alpha - \frac{\delta\gamma}{\mu + \delta})\frac{I}{\mu\kappa(h)}, I)}{I} - \frac{\mu + \gamma + \alpha - \frac{\gamma\delta}{\mu + \delta}}{\kappa(h)} = 0.$$

By the hypothesis  $(H_2)$ , g is strictly monotone decreasing on  $\left[0, \frac{A\kappa(h)}{(\mu+\gamma+\alpha-\frac{\gamma\delta}{\mu+\delta})}\right]$  satisfying:

$$\lim_{I \to 0^+} g(I) = \frac{(\mu + \gamma + \alpha - \frac{\gamma \delta}{\mu + \delta})}{\kappa(h)} (R_0 - 1) > 0,$$

and

$$g(\frac{A\kappa(h)}{(\mu+\gamma+\alpha-\frac{\gamma\delta}{\mu+\delta})}) = -\frac{(\mu+\gamma+\alpha-\frac{\gamma\delta}{\mu+\delta})}{\kappa(h)} < 0$$

Thus, there exists a unique  $I^*$  such that  $g(I^*) = 0$ . Hence, we conclude the existence and uniqueness of the endemic equilibrium  $P^*$ .

Finally, To prove global stability of the endemic equilibrium, we define a Lyapunov functional

$$V(t) = V_1(t) + V_2(t) + V_3(t) + V_+$$

with

$$V_1(t) = \int_0^h p(\tau) e^{-\mu\tau} d\tau (S - S^* - \int_{S^*}^S \frac{f(S^*, I^*)}{f(u, I^*)} du)$$
$$V_2(t) = (I - I^* - I^* \ln \frac{I}{I^*}),$$

and

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$$V_3(t) = \frac{\delta}{\mu + \delta} (R - R^* - R^* \ln \frac{R}{R^*}),$$

 $\quad \text{and} \quad$ 

$$V_{+} = \int_{0}^{h} \int_{t-\tau}^{t} p(\tau) e^{-\mu\tau} [(f(S,I) - f(S^{*},I^{*}) - f(S^{*},I^{*}) \ln \frac{f(S(u),I(u))}{f(S^{*},I^{*})})] du d\tau.$$

The time derivative of the function V(t) along the positive solution of system (1) is

$$\frac{\mathrm{d}V(t)}{\mathrm{d}t} = \int_{0}^{h} (p(\tau)e^{-\mu\tau})\mathrm{d}\tau \left(1 - \frac{f(S^{*}, I^{*})}{f(S, I^{*})}\right) \left(A - \mu S - f(S, I)\right) \\
+ \left(1 - \frac{I^{*}}{I}\right) \left(\int_{0}^{h} p(\tau)e^{-\mu\tau}f(S_{\tau}, I_{\tau})\mathrm{d}\tau + \delta R - (\mu + \alpha + \gamma)I\right) \\
+ \frac{\delta}{\mu + \delta} \left(1 - \frac{R^{*}}{R}\right) \left(\gamma I - (\mu + \delta)R\right) \\
+ \int_{0}^{h} (p(\tau)e^{-\mu\tau})[f(S, I) - f(S_{\tau}, I_{\tau}) + f(S^{*}, I^{*})\ln\frac{f(S_{\tau}, I_{\tau})}{f(S, I)}]\mathrm{d}\tau.$$
(8)

Using the relation  $A = \mu S^* + f(S^*, I^*)$ , simple calculations give that

$$\frac{\mathrm{d}V(t)}{\mathrm{d}t} = \int_{0}^{h} (p(\tau)e^{-\mu\tau})\mathrm{d}\tau \left[ \left( 1 - \frac{f(S^{*}, I^{*})}{f(S, I^{*})} \right) \left( -\mu(S - S^{*}) + f(S^{*}, I^{*}) \right) \right] \\
+ \int_{0}^{h} (p(\tau)e^{-\mu\tau})\mathrm{d}\tau \frac{f(S^{*}, I^{*})}{f(S, I^{*})} f(S, I) \\
- (\mu + \alpha + \gamma)I - e^{\mu\tau} \frac{I^{*}}{I} \int_{0}^{h} (p(\tau)e^{-\mu\tau})f(S_{\tau}, I_{\tau})\mathrm{d}\tau - \delta \frac{I^{*}}{I}R + (\mu + \alpha + \gamma)I^{*} \qquad (9) \\
+ \frac{\delta}{\mu + \delta} \left( \gamma I - \gamma I \frac{R^{*}}{R} + (\mu + \delta)R^{*} \right) \\
+ \int_{0}^{h} (p(\tau)e^{-\mu\tau})f(S^{*}, I^{*})\ln \frac{f(S_{\tau}, I_{\tau})}{f(S, I)}\mathrm{d}\tau.$$

Here by using

$$(\mu + \alpha + \gamma)I^* - \frac{\delta}{\mu + \delta}\gamma I^* = f(S^*, I^*) \int_0^h p(\tau)e^{-\mu\tau} \mathrm{d}\tau,$$

$$(\mu + \delta)R^* = \gamma I^*,$$

 $\quad \text{and} \quad$ 

$$\ln \frac{f(S_{\tau}, I_{\tau})}{f(S, I)} = \ln \frac{f(S^*, I^*)}{f(S, I^*)} + \ln \frac{I^* f(S_{\tau}, I_{\tau})}{I f(S^*, I^*)} + \ln \frac{I f(S, I^*)}{I^* f(S, I)},$$

straightforward calculations give

$$\begin{split} \frac{\mathrm{d}V(t)}{\mathrm{d}t} &= -\mu \int_{0}^{h} (p(\tau)e^{-\mu\tau}) \mathrm{d}\tau \Big(1 - \frac{f(S^{*}, I^{*})}{f(S, I^{*})}\Big) \Big(S - S^{*}\Big) \\ &- \int_{0}^{h} (p(\tau)e^{-\mu\tau}) \mathrm{d}\tau f(S^{*}, I^{*}) \Big(\frac{f(S^{*}, I^{*})}{f(S, I^{*})} - 1 - \ln \frac{f(S^{*}, I^{*})}{f(S, I^{*})}\Big) \\ &- f(S^{*}, I^{*}) \int_{0}^{h} (p(\tau)e^{-\mu\tau}) \Big(\frac{I^{*}f(S_{\tau}, I_{\tau})}{If(S^{*}, I^{*})} - 1 - \ln \frac{I^{*}f(S_{\tau}, I_{\tau})}{If(S, I^{*})}\Big) \mathrm{d}\tau \\ &+ f(S^{*}, I^{*}) \int_{0}^{h} (p(\tau)e^{-\mu\tau}) \mathrm{d}\tau \Big(\frac{f(S, I)}{f(S, I^{*})} - \frac{I}{I^{*}} + \frac{If(S, I^{*})}{I^{*}f(S, I)} - 1\Big) \\ &- f(S^{*}, I^{*}) \int_{0}^{h} (p(\tau)e^{-\mu\tau}) \mathrm{d}\tau \Big(\frac{If(S, I^{*})}{I^{*}f(S, I)} - 1 - \ln \frac{If(S, I^{*})}{I^{*}f(S, I)}\Big) \\ &+ \frac{\delta\gamma I^{*}}{\mu + \delta} \Big(2 - \frac{I^{*}R}{IR^{*}} - \frac{IR^{*}}{I^{*}R}\Big) \\ &= -\mu \int_{0}^{h} (p(\tau)e^{-\mu\tau}) \mathrm{d}\tau \Big(1 - \frac{f(S^{*}, I^{*})}{f(S, I^{*})}\Big) \Big(S - S^{*}\Big) \\ &- \int_{0}^{h} (p(\tau)e^{-\mu\tau}) \mathrm{d}\tau f(S^{*}, I^{*}) \Big(\frac{I^{*}f(S_{\tau}, I_{\tau})}{If(S^{*}, I^{*})} - 1 - \ln \frac{f(S^{*}, I^{*})}{f(S, I^{*})}\Big) \mathrm{d}\tau \\ &- f(S^{*}, I^{*}) \int_{0}^{h} (p(\tau)e^{-\mu\tau}) \Big(\frac{I^{*}f(S_{\tau}, I_{\tau})}{If(S^{*}, I^{*})} - 1 - \ln \frac{I^{*}f(S_{\tau}, I_{\tau})}{f(S, I^{*})}\Big) \mathrm{d}\tau \\ &- f(S^{*}, I^{*}) \int_{0}^{h} (p(\tau)e^{-\mu\tau}) \mathrm{d}\tau \Big(1 - \frac{f(S, I)}{If(S^{*}, I^{*})} - 1 - \ln \frac{I^{*}f(S_{\tau}, I_{\tau})}{f(S, I^{*})}\Big) \mathrm{d}\tau \\ &- f(S^{*}, I^{*}) \int_{0}^{h} (p(\tau)e^{-\mu\tau}) \mathrm{d}\tau \Big(1 - \frac{f(S, I)}{If(S^{*}, I^{*})} - 1 - \ln \frac{I^{*}f(S, I, I_{\tau})}{f(S, I^{*})}\Big) \mathrm{d}\tau \\ &- f(S^{*}, I^{*}) \int_{0}^{h} (p(\tau)e^{-\mu\tau}) \mathrm{d}\tau \Big(1 - \frac{f(S, I)}{If(S^{*}, I^{*})} - 1 - \ln \frac{I^{*}f(S, I, I_{\tau})}{f(S, I^{*})}\Big) \mathrm{d}\tau \\ &- f(S^{*}, I^{*}) \int_{0}^{h} (p(\tau)e^{-\mu\tau}) \mathrm{d}\tau \Big(\frac{If(S, I^{*})}{I^{*}f(S, I^{*})} - 1 - \ln \frac{If(S, I^{*})}{f(S, I)}\Big) \\ &- \frac{\delta\gamma}{\mu + \delta} \frac{IR^{*}}{R} \Big(\frac{I^{*}R}{IR^{*}} - 1\Big)^{2}. \end{split}$$

It follows from  $(H_1)$  and  $(H_2)$  that

$$-\mu \Big(1 - \frac{f(S^*, I^*)}{f(S, I^*)}\Big) \Big(S - S^*\Big) \le 0,$$

and

$$-f(S^*, I^*) \Big( 1 - \frac{f(S, I)}{f(S, I^*)} \Big) \Big( 1 - \frac{\phi(S, I^*)}{\phi(S, I)} \Big) \le 0.$$

Furthermore, since the function  $g(x) = 1 - x + \ln(x)$  is always non-positive for any x > 0, and g(x) = 0 if and only if x = 1, then  $\frac{dV(t)}{dt} \le 0$ , for all  $t \ge 0$ , where the equality holds only at the equilibrium point  $(S^*, I^*, R^*)$ . Hence,  $P^*$  is globally asymptotically stable.

**Remark 4.** In Proposition 3, by modifying Lyapunov function proposed in [6], we proved that the endemic equilibrium is globally asymptotically stable. The obtained result extended the Theorem (3.1) in [38]. But the Lyapunov function proposed in [38] is not valid for our model (1).

## **3** Numerical Simulations

In the following subsections, we will numerically indicate the risk of using the discrete or distributed time delay to describe the latent period. Also, we propose to illustrate graphically the effect of the relapse phenomenon on the basic reproduction number  $R_0$ .

First, in some cases the SIRI epidemic model with discrete delay and its corresponding version with distributed delay generate the same asymptotic behavior. However, we note significant differences in

the speed of convergence and the evolution of the infected individuals (see subsection 3.1). Second, we compared the basic reproduction number  $R_0$  of both models to bring out another major difference: the two models do not have the same equilibrium (see subsection 3.2). Finally, we illustrate the effect of the rate of relapse on the reproduction number  $R_0$  and we observe that the relapse phenomenon increases the risk of installation of the disease in the considered population (see subsection 3.3).

#### 3.1 Effect of the Latent Period on the Asymptotic Behavior

In this subsection, we give a numerical simulation to illustrate the theoretical analysis given in section 2 and to compare a distributed SIRI model (1) with the following discrete SIRI model (SIRI model with constant time delay) [6]:

$$\begin{cases} \frac{\mathrm{d}S}{\mathrm{d}t} = A - \mu S - f(S, I), \\ \frac{\mathrm{d}I}{\mathrm{d}t} = e^{-\mu h} f(S_h, I_h) - (\mu + \gamma + \alpha)I + \delta R, \\ \frac{\mathrm{d}R}{\mathrm{d}t} = \gamma I - (\mu + \delta)R. \end{cases}$$
(11)

Let

$$f(S, I) = \beta SI \quad and \quad p(\tau) = \frac{1}{h}$$

Applying Mickens nonstandard discretization (see, [43,44,45]) to the continuous model (1), we first derive the following discretized SIRI epidemic model with a distributed time delay:

$$\begin{cases} S_{n+1} - S_n = A - \mu S_{n+1} - \beta S_{n+1} I_{n+1}, \\ I_{n+1} - I_n = \frac{\beta}{h} \sum_{k=0}^{h} e^{-\mu k} S_{n-k} I_{n-k} - (\mu + \gamma + \alpha) I_{n+1} + \delta R_{n+1}, \\ R_{n+1} - R_n = \gamma I_{n+1} - (\mu + \delta) R_{n+1}, n = 0, 1, 2, \dots \end{cases}$$
(12)

The initial conditions of the system (12) are given by

$$S_n = \psi_n^{(1)} \ , \ I_n = \psi_n^{(2)} \ , \ R_n = \psi_n^{(3)} \ , \ for \ , \ n = -h \ , \ -h + 1 \ , \ ..., 0,$$

where  $\psi_n^{(i)} \ge 0$  ( n = -h , -h + 1 , ..., 0 , i = 1, 2, 3 ). We further assume that  $\psi_0^{(i)} > 0$  for i = 1, 2, 3.

Substituting the third equation into the second equation of (12), we consider the following system:

$$\begin{cases} S_{n+1} = \frac{A + S_n}{1 + \mu + \beta I_{n+1}}, \\ I_{n+1} = \frac{\beta}{(1+c)h} \sum_{k=0}^h e^{-\mu k} S_{n-k} I_{n-k} + \frac{I_n}{1+c} + c_1 R_n, \\ R_{n+1} = \frac{\gamma}{1 + (\mu + \delta)} I_{n+1} + \frac{R_n}{1 + (\mu + \delta)}, \end{cases} \end{cases}$$

with

$$c = \frac{(\mu + \gamma + \alpha) + (\mu + \delta)(\mu + \alpha) + \mu\gamma}{1 + (\mu + \delta)} \quad and \quad c_1 = \frac{\delta}{1 + (\mu + \delta)} \frac{1}{(1 + c)}$$

Therefore we have

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$$\begin{cases} S_{n+1} = \frac{A+S_n}{1+\mu+\beta[\frac{\beta}{(1+c)h}\sum_{k=0}^{h}e^{-\mu k}S_{n-k}I_{n-k} + \frac{I_n}{1+c} + c_1R_n]}, \\ I_{n+1} = \frac{\beta}{(1+c)h}\sum_{k=0}^{h}e^{-\mu k}S_{n-k}I_{n-k} + \frac{I_n}{1+c} + c_1R_n, \\ R_{n+1} = \frac{\gamma}{1+(\mu+\delta)}[\frac{\beta}{(1+c)h}\sum_{k=0}^{h}e^{-\mu k}S_{n-k}I_{n-k} + \frac{I_n}{1+c} + c_1R_n] + \frac{R_n}{1+(\mu+\delta)}. \end{cases}$$
(13)

We take the parameters of the system (1) as follows:

$$\begin{split} A &= 5, \quad \mu = 0.005, \quad \gamma = 0.02, \quad \alpha = 0.005, \\ \beta &= 0.1, \quad \delta = 0.001, \quad h = 10, \quad S(0) = 999, \quad I(0) = 1, \quad R(0) = 0 \end{split}$$

By Proposition 3, the endemic equilibrium  $P^*$  of the distributed SIRI model (1) is globally asymptotically stable (see Fig. 1). In addition, the models (1) and (11) generate identical, global asymptotic behavior with different rates of convergence: For example, the maximum of infectious individuals is achieved, for the model (1), at time t = 500 days (1 years and 4 months), but this maximum is reached, for the model (11), before 200 days (see Figure 1 and Figure 2).



Figure 1. Solutions (S, I, R) of the distributed SIRI epidemic model (1) are globally asymptotically stable and converge to the endemic equilibrium  $P^*$ .



Figure 2. Solutions (S, I, R) of a discrete SIRI epidemic model (11) are globally asymptotically stable and converge to the endemic equilibrium  $P^*$ 

#### 3.2 Effect of the Latent Period on the Basic Reproduction Number

Now, we will show how the basic reproduction number  $R_0$  changes depending on the latent period. In table 1, we assume that the parameters

$$A = 5, \quad \alpha_1 = 0.9, \quad \alpha_2 = 0.9, \quad \mu = 0.005, \quad \gamma = 0.02,$$
  
$$\alpha = 0.005, \quad \beta = 0.1, \quad \delta = 0.001.$$

are fixed and

$$f(S,I) = \frac{\beta SI}{1 + \alpha_1 S + \alpha_2 I}, \quad p(\tau) = \frac{1}{h}.$$

The distributed SIRI epidemic model (1) and the discrete SIRI epidemic model (11) generate the same global asymptotic stability for certain values of h. However for  $h \in [286, 810]$  this equivalence was not true: the system (1) has the disease free equilibrium and the endemic equilibrium  $(R_0 > 1)$ , but the system (11) has only a disease free equilibrium  $(R_0 \leq 1)$  (see, Table 1).

Table 1	. Dependence of	the basic rep	production r	number <i>l</i>	$R_0$ on a	distributed	and a	discrete	latent	period
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h(days)	$R_0$ of a discrete latent period	$R_0$ of a distributed latent period
200	1.53	2.63
285	1.00	2.22
286	0.99	2.21
290	0.98	2.20
300	0.93	2.15
819	0.07	0.99

#### 3.3 Effect of the Relapse Rate on the Basic Reproduction Number

The basic reproduction number  $R_0$  is a strictly monotonically increasing function of relapse rate  $\delta \left(\frac{dR_0}{d\delta} > 0\right)$  (see Fig. 3). Therefore, the relapse is a factor favoring the installation of the disease in the concerned population by increasing the value of  $R_0$  at a higher level to one. Moreover, ignoring the relapse in an epidemiological model will underestimate  $R_0$ .



**Figure 3.** Dependance of the basic reproduction number on the relapse rate of the distributed SIRI epidemic model for A = 5; h = 10;  $\alpha_1 = 0.9$ ;  $\alpha_2 = 0.9$ ;  $\mu = 0.005$ ;  $\gamma = 0.02$ ;  $\alpha = 0.005$ ; and  $\beta = 0.1$ 

### 4 Conclusion and Future Research

In recent years, modeling the latent period by a distributed time delay has more attracted the attention of mathematical researchers, because the experiments and the statistical studies for some diseases have shown that this period may be modeled by distributed time delay. Moreover, the distributed delay is used in the epidemiological models to examine the cumulative effect of the incidence function.

In this work, we presented a mathematical analysis for a SIR epidemiological model with a distributed delay, a general incidence function and the relapse phenomenon (1). The originality of this work is to have a basic reproduction number  $R_0$  which depends on the distribution of the latent period. This number remains a key parameter for the stability analysis of epidemiological models: if  $R_0 \leq 1$ , then the disease free equilibrium is globally asymptotically stable and if  $R_0 > 1$ , then the unique endemic equilibrium is globally stable.

In addition, we proved that: On one hand, the dynamics of the discrete SIRI model (11) is different, in some senses, to the one given by the distributed SIRI model (1) (see Fig. 1, Fig. 2 and Table 1). On the other hand, the relapse is a factor favoring the installation of the disease by increasing the value of  $R_0$  at a higher level to one  $\left(\frac{dR_0}{d\delta} > 0\right)$ .

For the future research, we will consider an SIRI model with a non-constant total population, a logistic recruitment, a non-linear relapse rate and an anti-relapse treatment.

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